

# Improving Weld Productivity and Quality by means of Intelligent Real-Time Close-Looped Adaptive Welding Process Control through Integrated Optical Sensors

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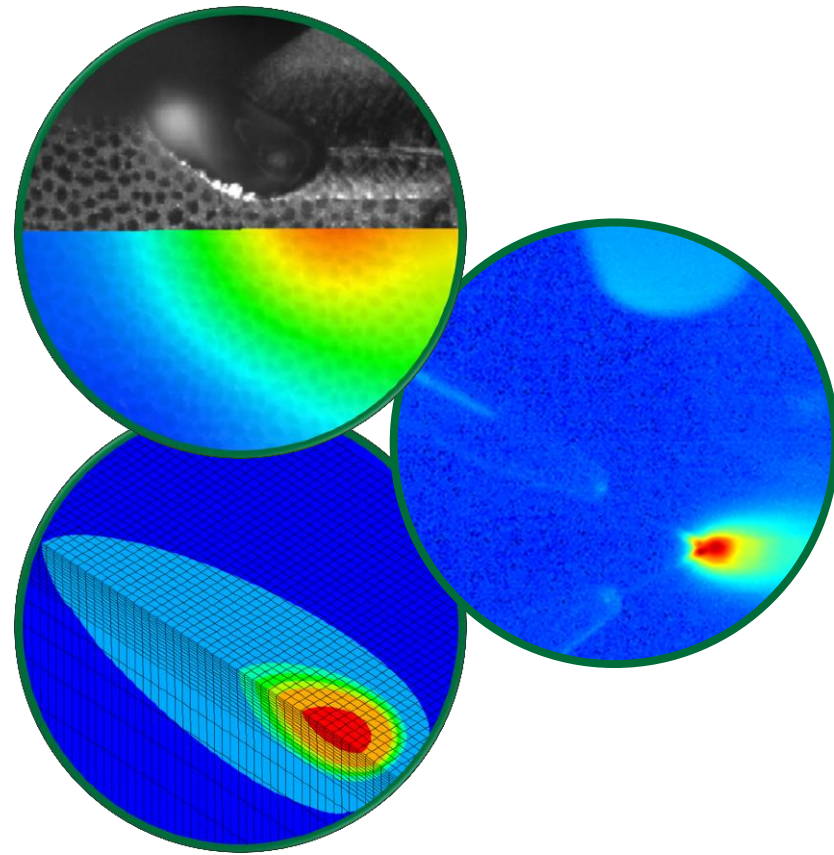
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# Overview

- NEET1- Advanced Methods for Manufacturing
- Time line
  - Start: October, 2014
  - End: September, 2017
- Total project funding from DOE: \$800K
- Technical barrier to address
  - Advanced, high-speed and high-quality welding technologies

## FINANCIAL ASSISTANCE FUNDING OPPORTUNITY ANNOUNCEMENT



U. S. Department of Energy

Idaho Operations Office

Fiscal Year 2014 Consolidated Innovative Nuclear Research

Funding Opportunity Announcement:  
DE-FOA-0000998

Announcement Type: Initial

CFDA Number: 81.121

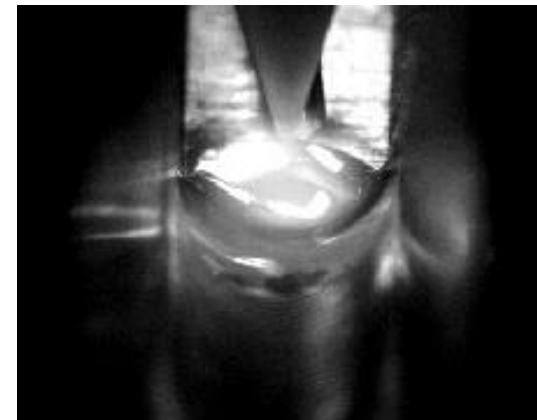
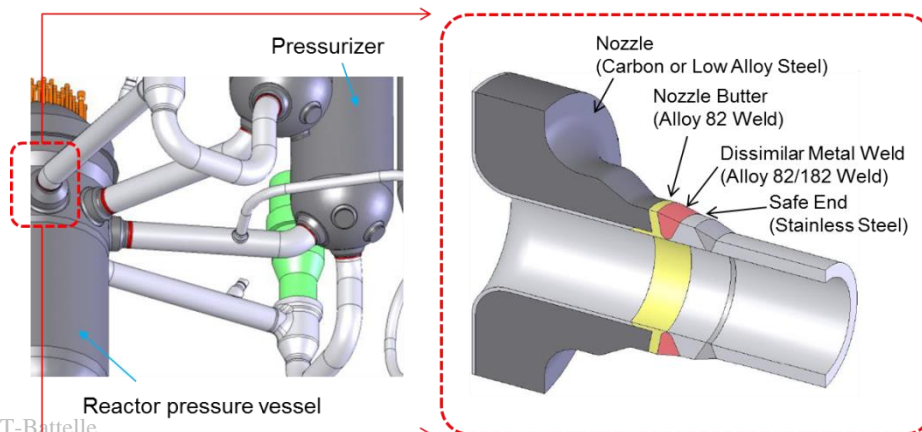
Issue Date: October 31, 2013

Pre-Application (Mandatory) Due Date: December 2, 2013 at 8:00 PM ET

Application Due Date: April 3, 2014 at 8:00 PM ET

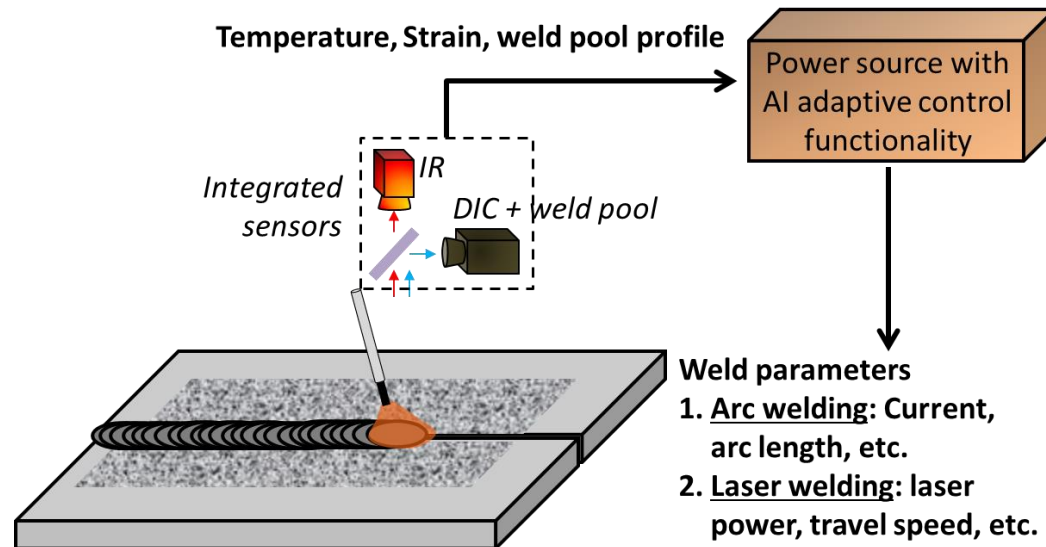
# Objective

- This project aims at developing a welding quality monitoring and control system based upon *multiple optical sensors*.
  - Enables real-time weld defect detection and adaptive adjustment to the welding process conditions to eliminate or minimize the formation of major weld defects.
  - Addresses the needs to develop “advanced (high-speed, high quality) welding technologies” for factory and field fabrication to significantly reduce the cost and schedule of new nuclear plant construction.



# Principal

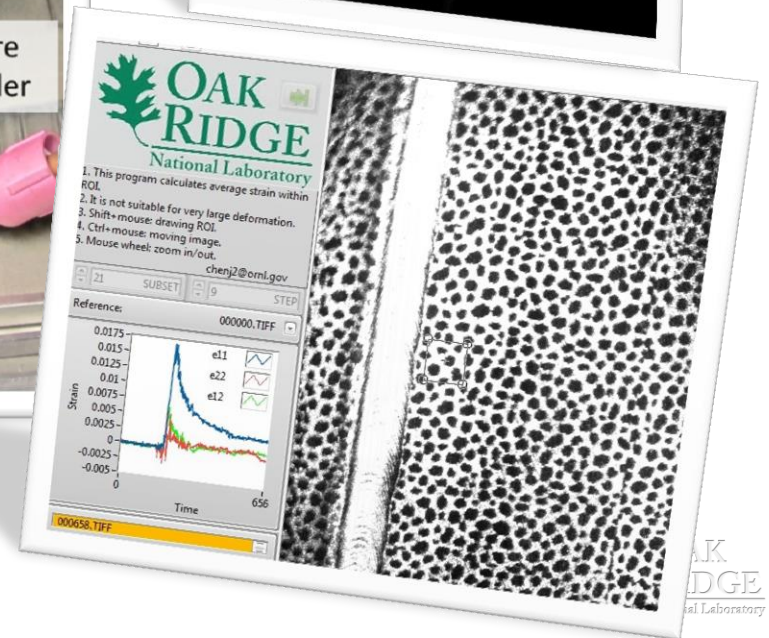
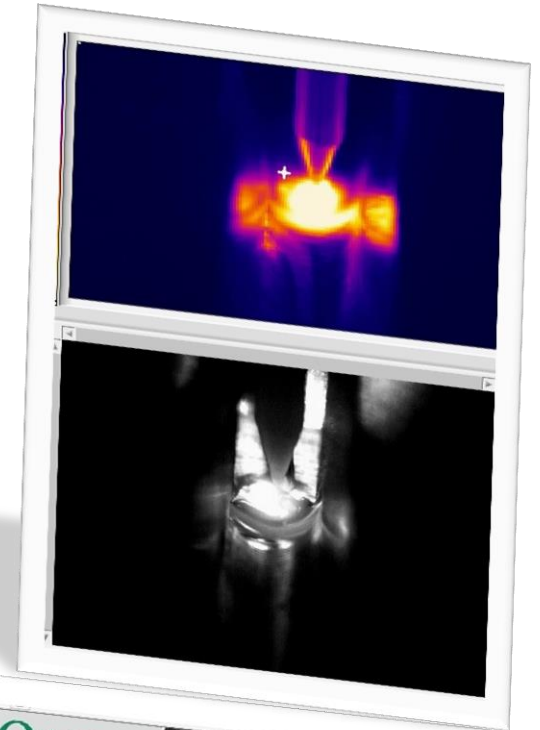
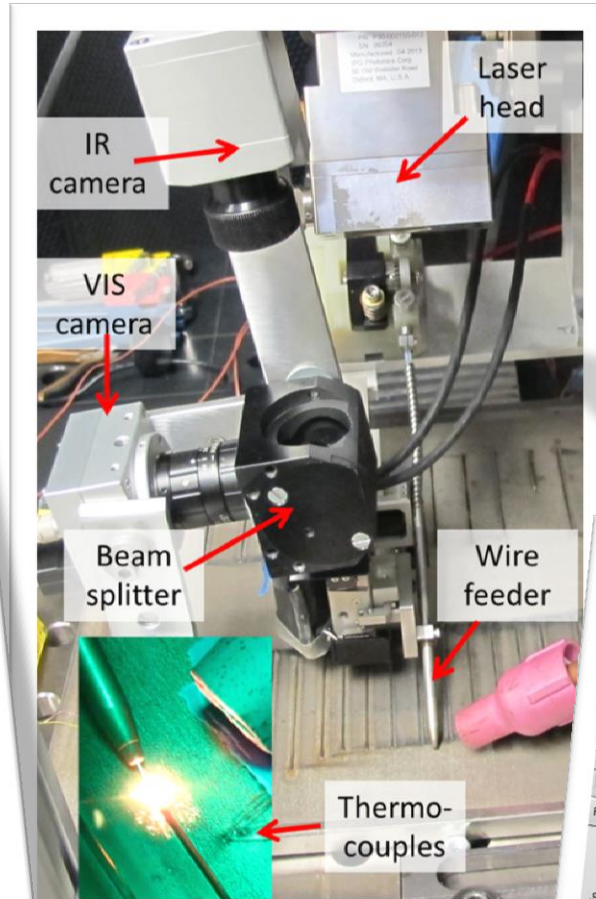
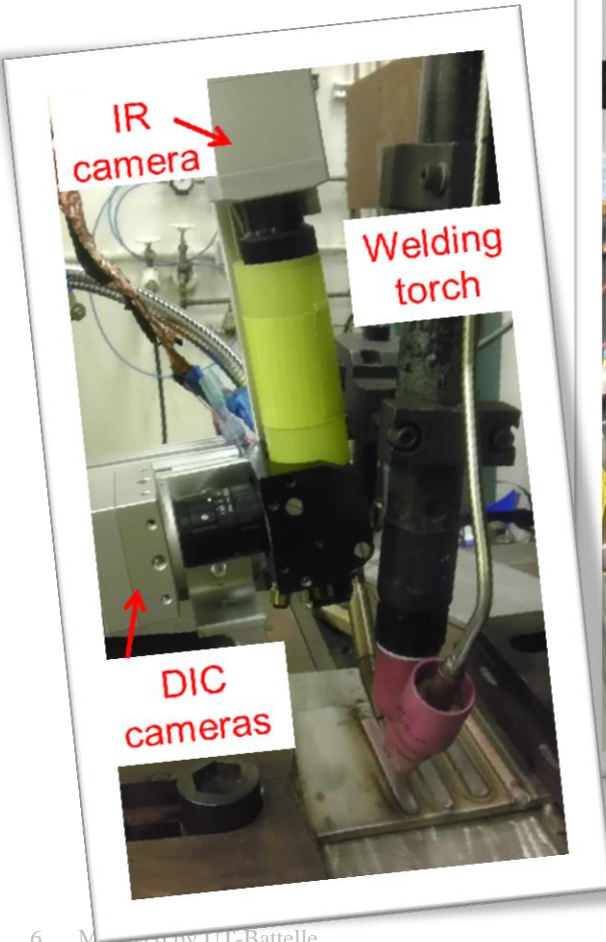
- **Non-contact** optical monitoring system for inspecting each weld pass
- Building a foundation of signal/knowledge database from past experiences to detect certain types of weld defects
  - Temperature field
  - Strain/stress field (related to residual stress, distortion, cracks, etc.)
  - Weld pool surface profile (related to bead shape, lack of penetration, etc.)
- Close-looped adaptive welding control algorithm will correlate the above measurement signals to the weld quality and provide feedback control signals in real time



# Current accomplishments

- System development
  - Hardware: cameras, optical illumination and filtering systems, I/O connections, etc.
  - Software: hardware control, data acquisition and analysis
- Development of new sensing methods and algorithms
  - Novel high-temperature DIC method and algorithm
    - Real-time temperature, strain and stress monitoring in HAZ
  - Weld pool visualization and surface dynamics
    - Defects identification and penetration control

# Hardware integration and software development



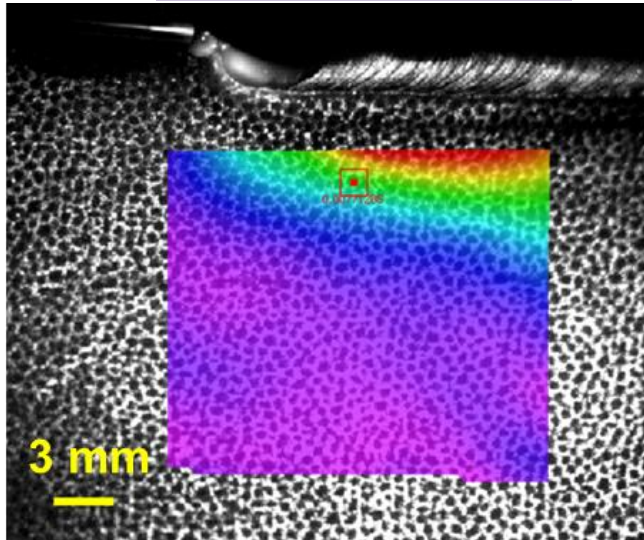
# Novel high-temperature DIC for strain measurement

- DIC is a noncontact optical method to measure surface strain.
- The application in in-situ welding monitoring has been very challenging

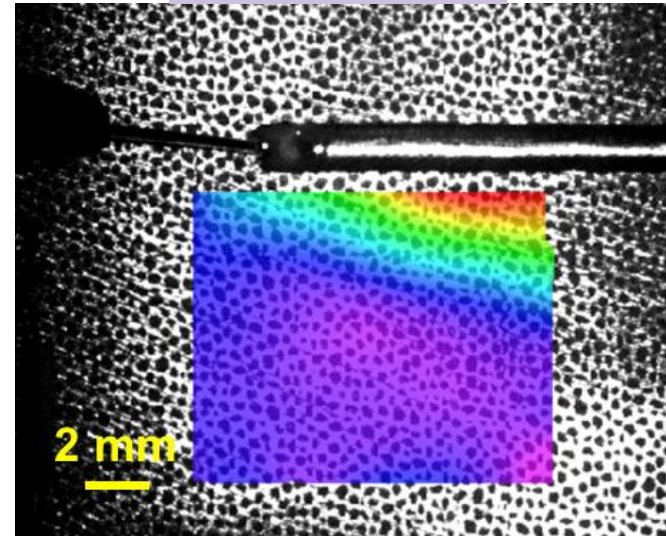
Challenges	Solutions
Intense arc light	Special optical illumination and filtering system
Damage/burning of speckle pattern	Novel speckle patterns survived at temperature up to the melting point
Specular reflection on metal surface	Novel stereo (3D) DIC algorithm
Real-time data processing	In-house software

# Special optical system and high-temperature speckle\*

Arc welding (TIG)



Laser welding



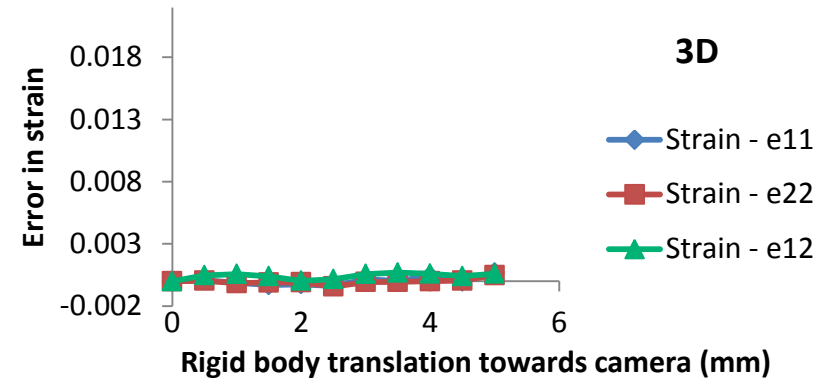
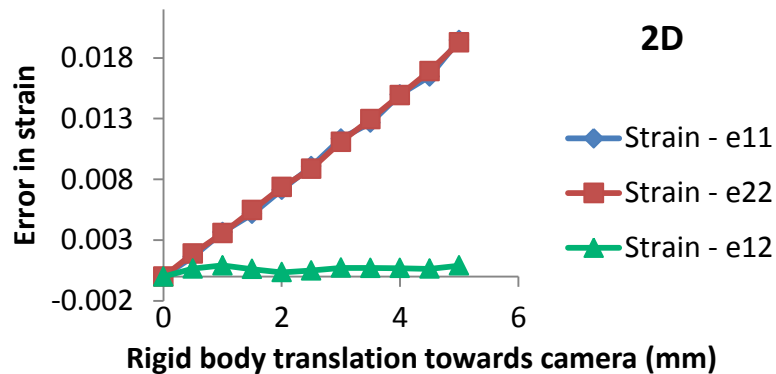
- Basic requirements of DIC algorithm: stable illumination and stable speckle pattern
  - Special illumination and filtering system to greatly suppress the intense welding arc or laser plume
  - Novel speckle pattern survived at temperatures up to the melting point

\* J.Chen, X.Yu, R.G.Miller, Z.Feng, "In-situ Strain and Temperature Measurement and Modeling during Arc Welding", *Science and Technology of Welding and Joining*, Volume 20, Issue 3 (March 2015), pp. 181-188



# Novel 3D DIC method on specular surface

- Why 3D DIC (stereo camera setup)?
  - Large error is expected for 2D DIC (one single camera) setup when out-of-plane displacement occurs



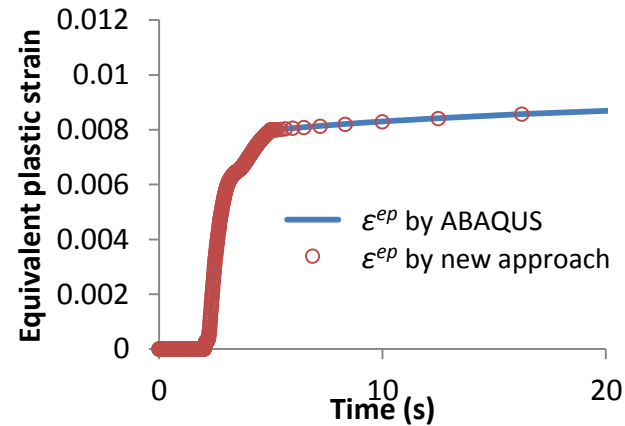
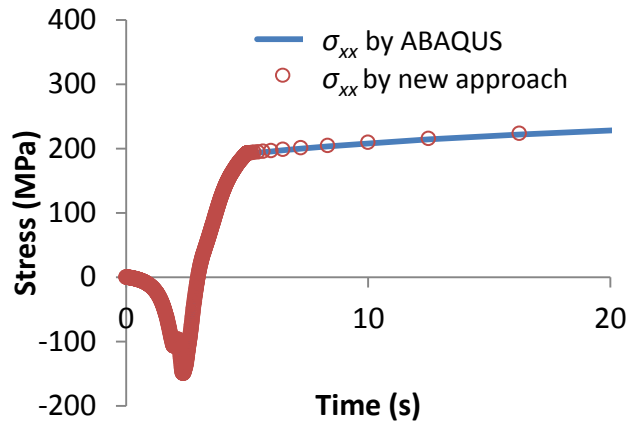
- Conventional (commercial) 3D DIC codes does NOT work on specular metal surface
  - Projected speckle pattern to both cameras can be totally different causing issues in pattern matching
- Novel 3D DIC algorithm and procedure has been developed
  - Works for both specular and diffuse surfaces

# Beyond strain: real-time stress calculation

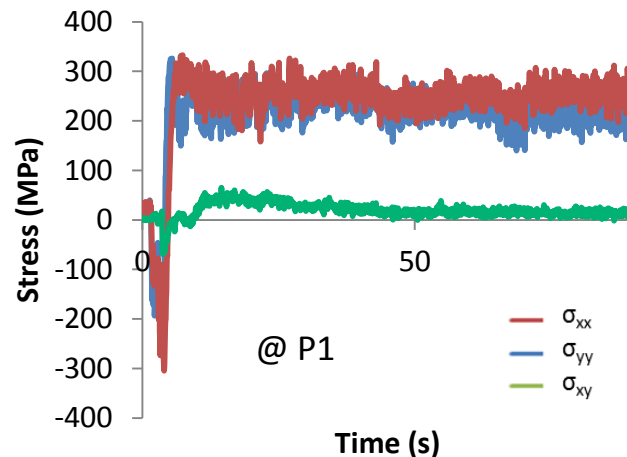
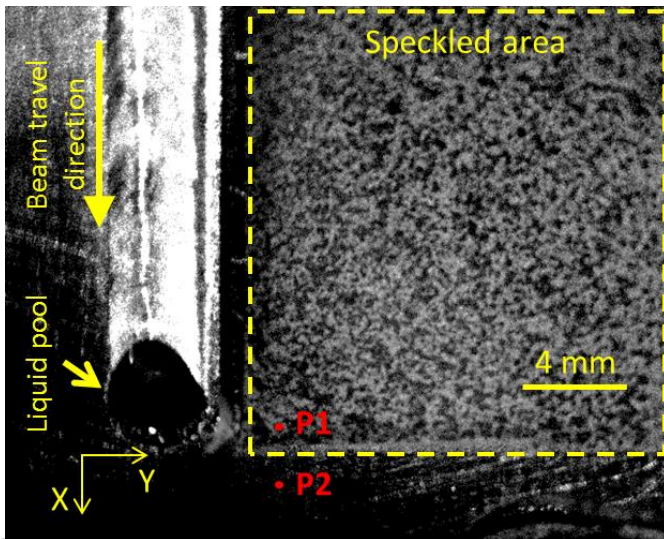
- The evolution of stress is directly correlated to certain weld attributes/defects (distortion, residual stress, etc.)
- A new algorithm has been integrated to calculate stress in real time based on in-situ strain and temperature measurements
  - Works for both elastic and plastic deformation
  - without the complication of numerical models
- The new algorithm is under patent application. Details are not disclosed herein

# Stress calculation

- Algorithm is validated by a simulated welding process



- Real-time stress monitoring during laser welding



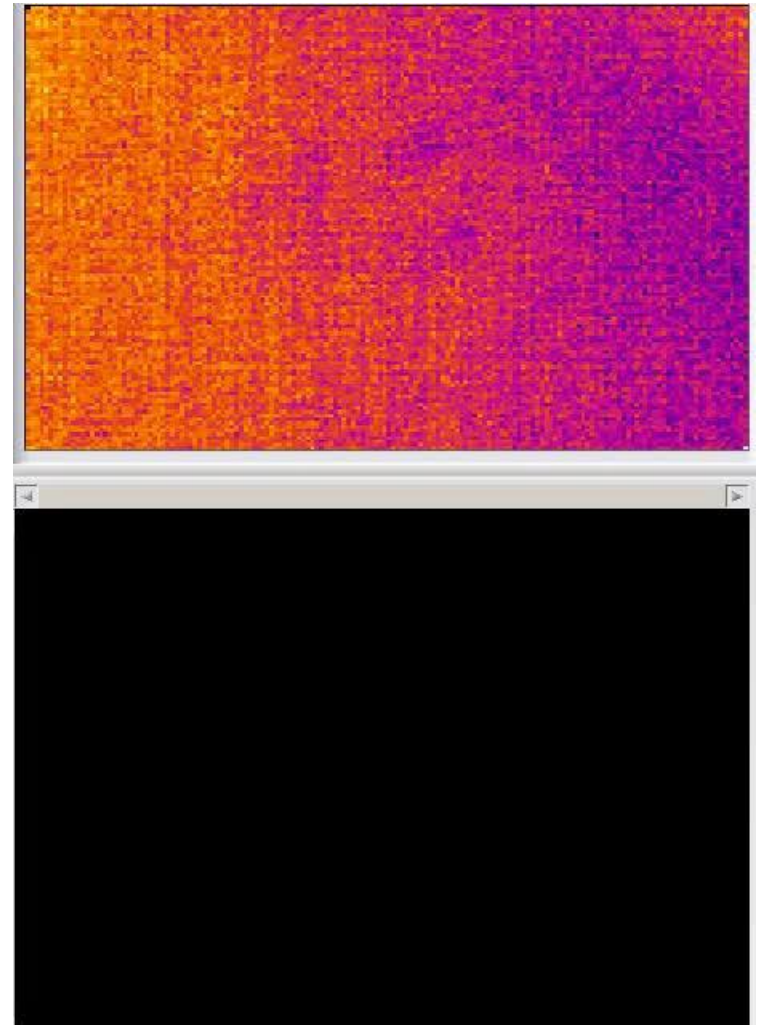
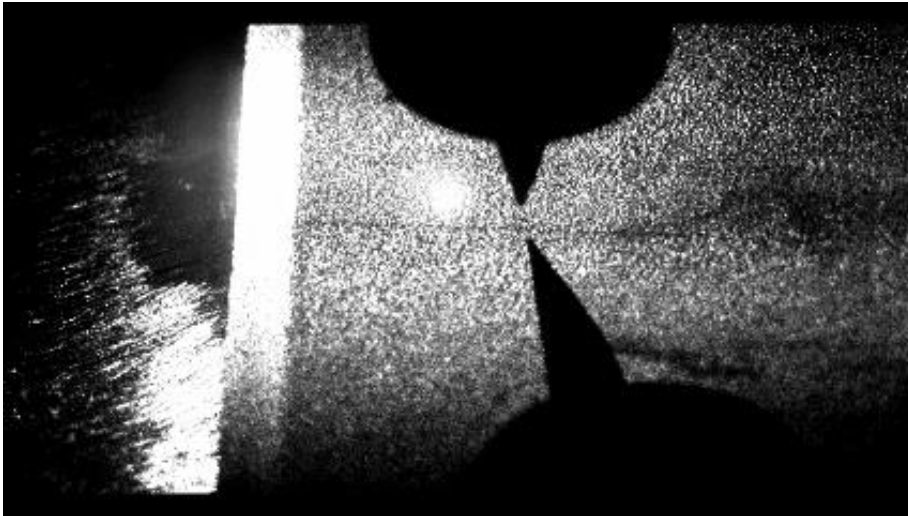
XRD measured residual stress

@ P2:

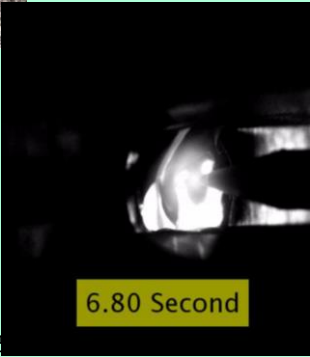
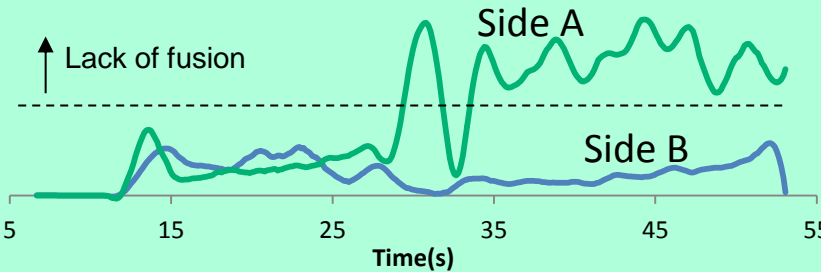
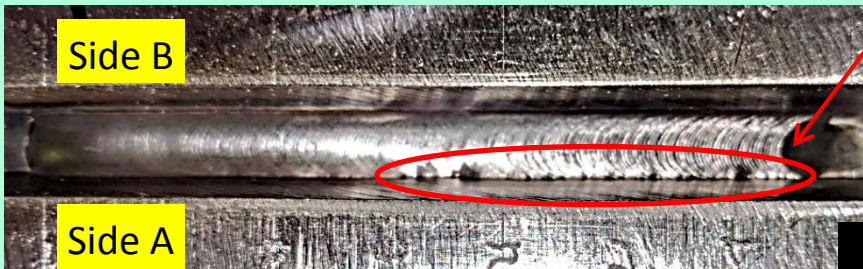
$\sigma_{xx}$ =221 MPa

$\sigma_{yy}$ =324 MPa

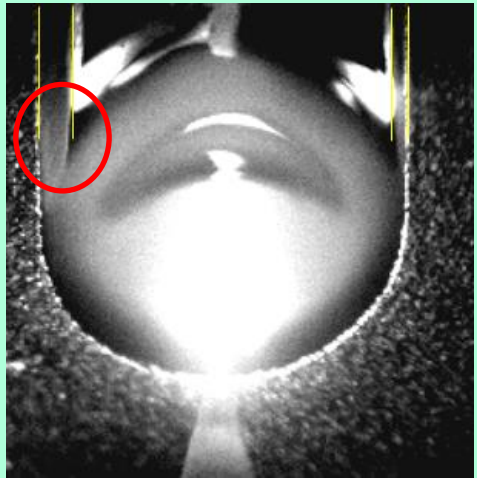
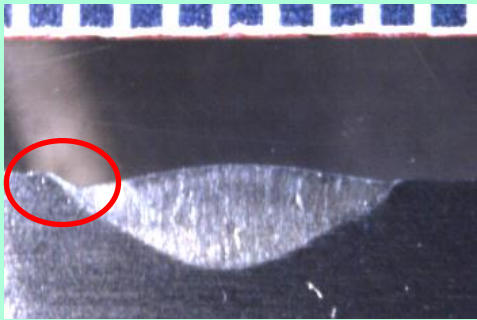
# Weld pool visualization



# Defects detection

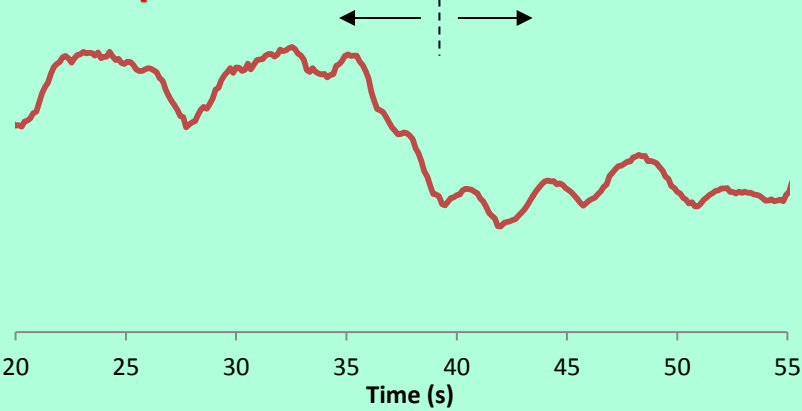


## Undercutting

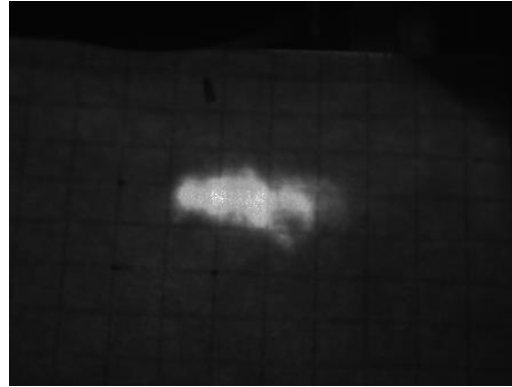
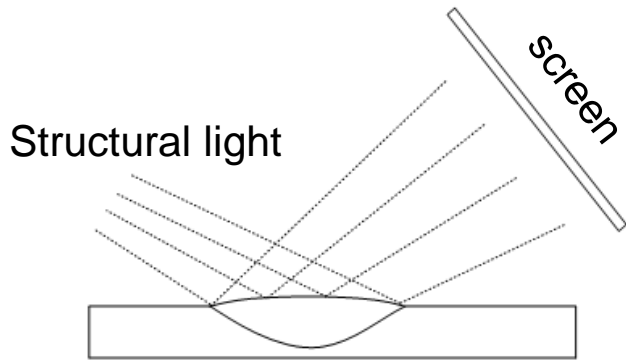


## Partial penetration

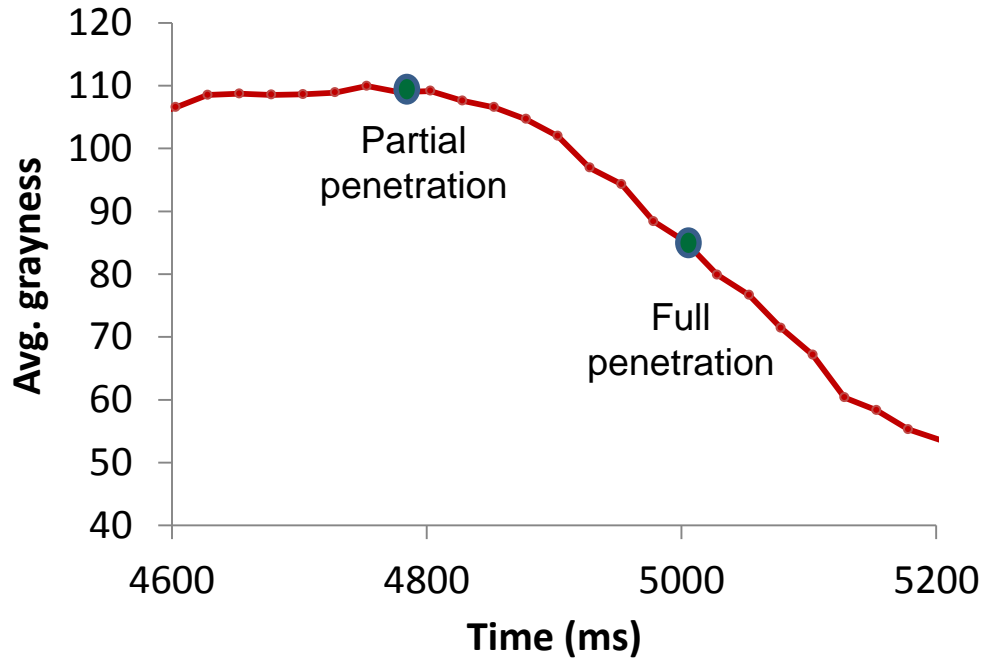
## Full penetration



# Penetration depth by light reflection



Average grayness varies due to the transition of surface vibration from partial to full penetration.



# Weld pool dynamic model and full penetration control

$$Y(k + 1) = 1.06 * Y(k) - 0.098 * u(k)$$

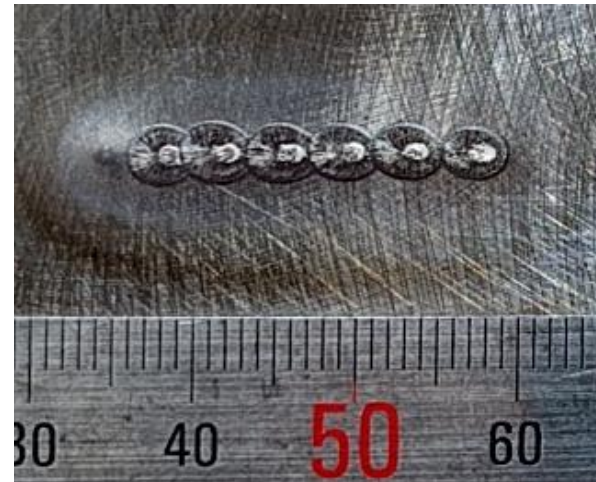
$Y$  - image grayness

$u$  - welding current

Front side



Back side



# Summary

- A multi-optical sensing system was integrated and tested for monitoring arc welding and laser welding processes.
- Novel methods and algorithms were developed for real-time strain and stress monitoring in HAZ.
- Defects such as lack of fusion and undercutting were positively identified.
- Penetration depth was correlated to the grayness of the reflected structural light, based on which a full-penetration control algorithm was developed.



# Next Steps

- Continue to refine and optimize the multi-optical system (hardware and software).
  - To get more reliable signals
  - To detect more types of weld defects
- Further develop control algorithms to minimize or avoid the formation of the detectable defects.
- Build a working prototype system for demonstration.

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**Thank you!**

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